

Outage Probability of an OTFS System in High Mobility Scenario

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Abstract

In this paper, we present the outage probability performance of orthogonal time frequency space (OTFS) system in high mobility scenario. The results confirm again that the OTFS provides a higher diversity order as the mobile speed increases even when the multipath intensity profile is identical.

I. Introduction

Orthogonal time frequency space (OTFS) modulation which uses two-dimensional domain to multiplex the information symbols, referred to as delay-Doppler (DD) domain, has lately received a lot of attention as a strong candidate for beyond 5G (B5G) communication systems due to its robust performance against high Doppler [1]. Also, to design OTFS-based systems, its different parameters need to be studied [2]. Therefore, this work shows outage probability performance of OTFS system and how this performance changes for the system under different mobility scenario [2].

II. System Model

We consider an OTFS frame consists of $M \times N$ symbols in a single frame. These symbols are placed on a grid in the delay-Doppler (DD) domain, which through OTFS modulation are transformed to delay-time (DT) domain. Let $\mathbf{X} \in \mathbb{C}^{M \times N}$ be information symbol matrix in DD domain, and $\tilde{\mathbf{X}} = \mathbf{X} \mathbf{F}_N^H$ be the DT signal, where \mathbf{F}_N is the N point normalized discrete Fourier transform (DFT) matrix. The time domain signal is formed by adding cyclic prefix (CP) to each time symbol. The received signal $\mathbf{Y} = \tilde{\mathbf{Y}} \mathbf{F}_N$ after passing through a time-varying high mobility channel in the delay-Doppler domain can be expressed as follows

$$\mathbf{y} = \text{vec}(\mathbf{Y}) = \mathbf{H}\mathbf{x} + \mathbf{w} \in \mathbb{C}^{NM \times 1} \quad (1)$$

where $\mathbf{x} = \text{vec}(\mathbf{X}) \in \mathbb{C}^{NM \times 1}$, $\mathbf{H} \in \mathbb{C}^{NM \times NM}$ is the delay-Doppler channel matrix, and \mathbf{w} is the delay-Doppler additive white Gaussian noise (AWGN) vector.

The capacity of the system from (1) is given as

$$C = \frac{1}{NM} \log_2 \left| \mathbf{I}_{NM} + \frac{E_s \mathbf{H} \mathbf{H}^H}{\sigma^2} \right| \quad (2)$$

The outage probability of the system is further given by

$$P_{out} = \Pr \left\{ C = \frac{1}{NM} \log_2 \left| \mathbf{I}_{NM} + \frac{E_s \mathbf{H} \mathbf{H}^H}{\sigma^2} \right| < R \right\} \quad (3)$$

where R is the target rate.

III. Simulations and Results

For performance evaluation we have considered an OTFS system with the target rate $R = 2$ bits/s/Hz, $M \times N = 64 \times 16$, $\Delta f = 15$ KHz, and carrier-frequency of 4×10^9 Hz. The channel is generated by considering the delay-profile and power delay profile of extended vehicular A (EVA) model with $L = 9$ taps and $L_{\max} = 2$ and different user velocities $v = 100$ km/h, 500 km/h and 1000 km/h. The systems is

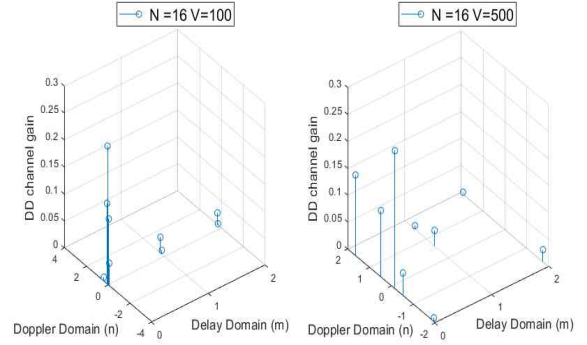


Fig. 1 DD channel under different user velocities

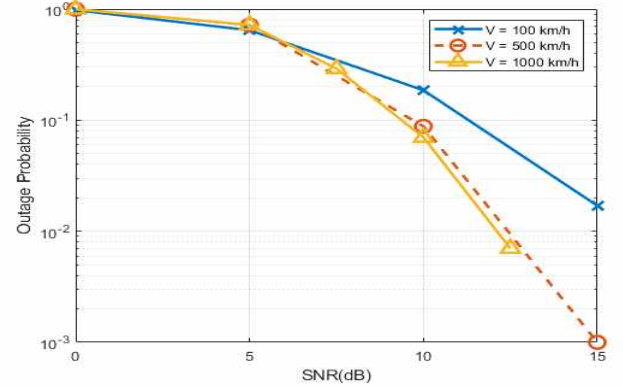


Fig. 2 Outage probability versus SNR for different user velocities

considered under fractional Doppler, and each Doppler tap of the channel is taken from Jakes' model $v_i = v_{\max} \cos(\theta_i)$, where $\theta_i = \text{Uniform}(0, 2\pi)$. Fig. 1 shows a random realization of DD channels under mentioned user velocities, wherein we can see that the channel with user velocity 500 km/h has more resolvable paths, which is also true on average for large channel realizations. Thus, the diversity order of the system increases with velocity. The results in Fig. 2 also confirm our observation as the outage performance of the system improves with increase in user velocities.

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